

3D geometry recognition by RFID-Box based on deep learning



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3D geometry recognition for garment telemarketing

- Limitation in camera-based virtual fitting :
 - High cost of geometry reconstruction in terms of merging the camera images from multiple angles.
 - Privacy concern when the user has to be in front of multiple cameras without clothing or with snug-fit thin fabrics.
- 3D geometry recognition using RFID box or closet:
 - Cost-effective.
 - Maintenance-free passive tags.
 - Convenient deployment and easily portable.
 - No privacy concern not only because no camera is used, but also because the user can be in their daily garment for the body shape.



3D geometry recognition for gesture identification

- Convenient setup for accurate static hand gesture recognition.
- Facilitate Human Computer Interaction (HCI) applications including 3D virtual reality control and sign-language detection.

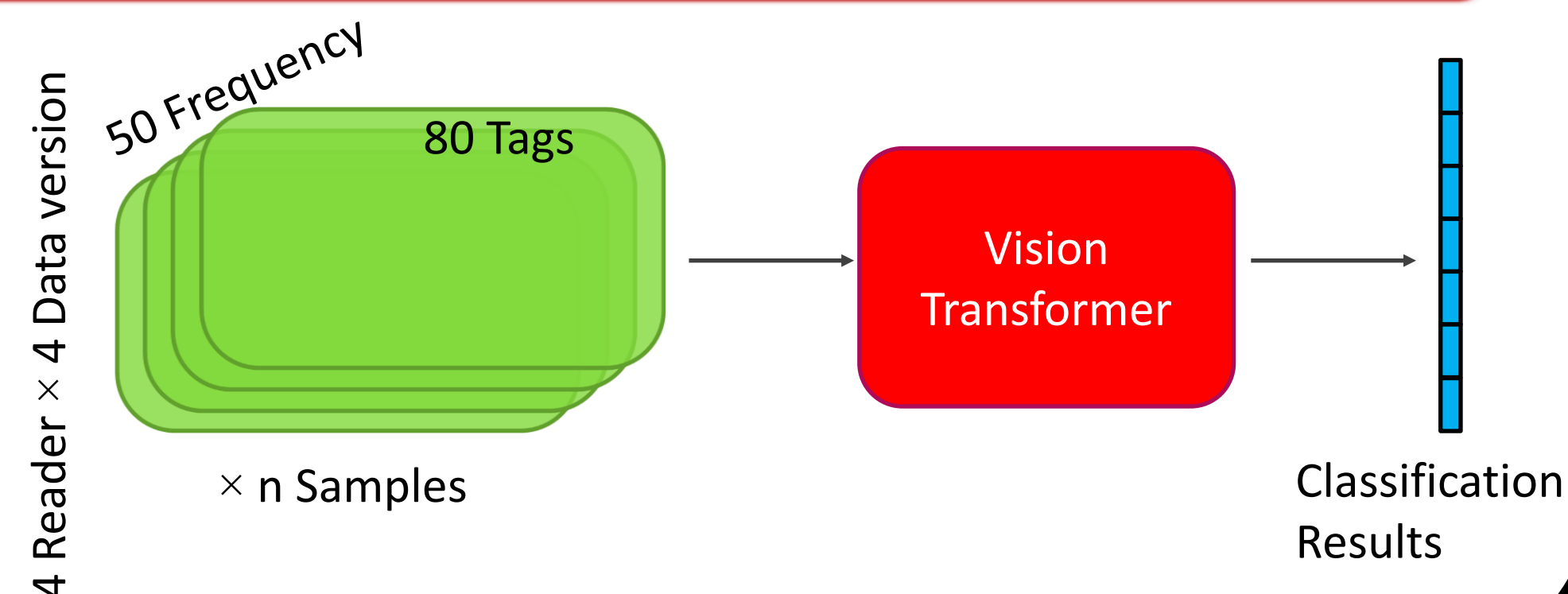
Passive UHF RFID tags for spatial diversity in RFID-Box

- 80 commercial passive RFID tags were lined inside the four peripheral sides of a cubic cardboard box of 45 cm.
- Four reader antennas were placed at the bottom driven from the Impinj reader running EPC Gen 2.
- 50 carrier frequencies in the range of 902-928 MHz were used. Reader antennas employed time division multiplexing (TDM).
- The reader Rx retrieved the tag ID, RSSI, phase, carrier frequency, and reader antenna port after 1 minute data collecting.

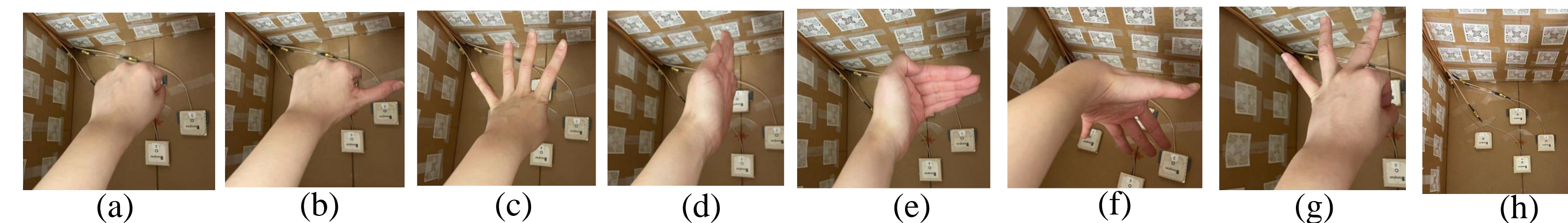


Deep learning model for geometry recognition

- The reader outputs were pre-processed by 2D image-like spectrogram and then fed into the Vision Transformer (ViT) as the deep learning model for geometry classification.



Static hand gesture recognition in RFID-Box



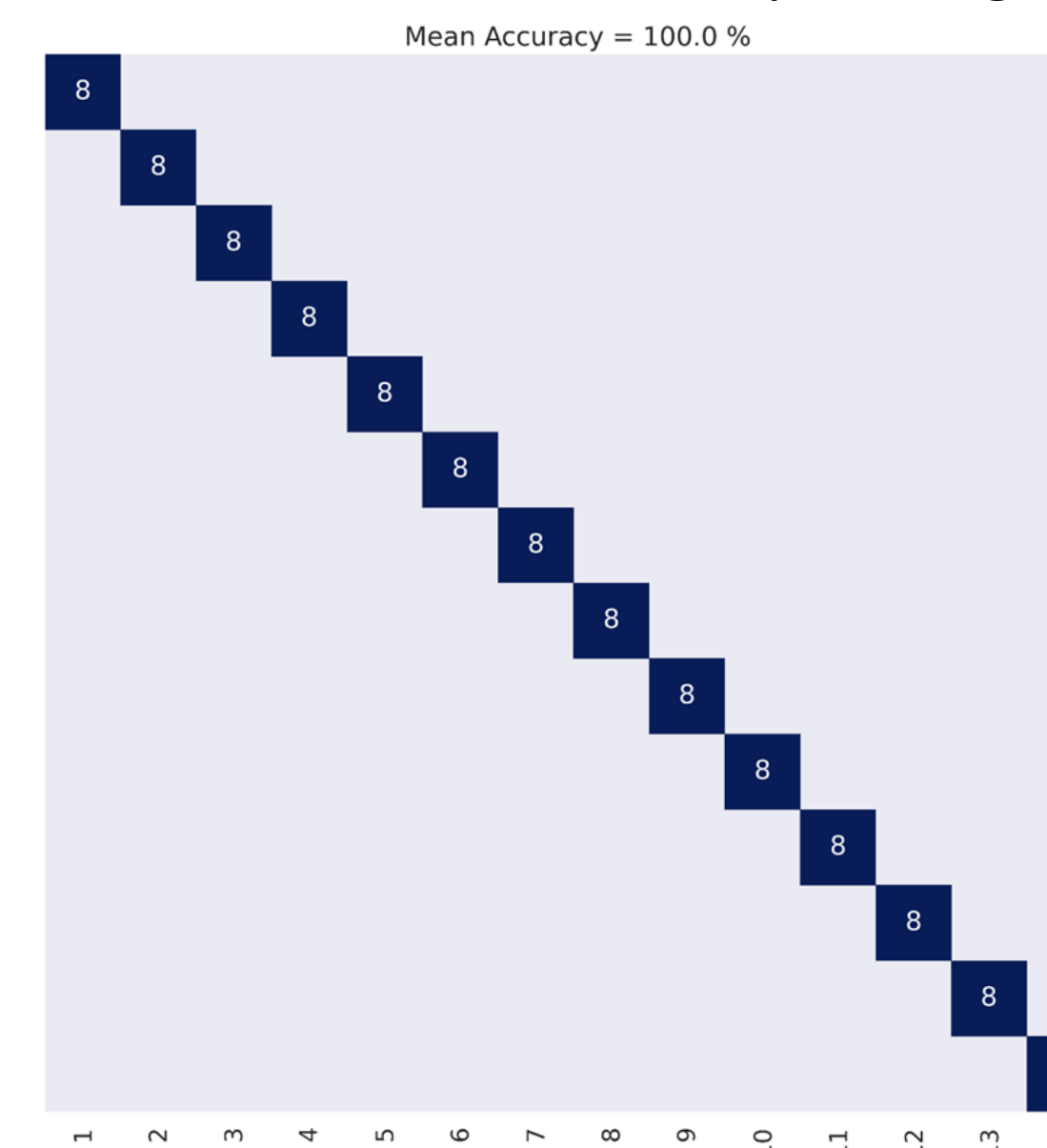
Testing accuracy for 8 hand gesture categories

Participants	P1	P2	P3	P1 (with glove)	P1+ P2
Sample size	80	49	52	43	129
Accuracy (%)	100	100	100	95.3	99.2

- K-fold (k = 6) cross validation was performed to estimate the mean accuracy.
- Built the personal training model for static gesture geometry recognition, and tested on 3 participants to demonstrate the ready generalization to gestures across different persons.
- For evaluation of the capability to distinguish individual participants, the system achieved 100% accuracy on distinguishing the participant from P1 and P2.

Geometry recognition in RFID-Box

Confusion matrix for 14 shape recognition



- Tested on objects wrapped in aluminum foils.
- 14 shapes consist of Lego blocks (4"×4"×2") with additional thin layers (3"×3"×0.5"), imitating shoe size fitting.
- Spatial resolution: around 0.25" until recognition accuracy starts to degrade.



Future improvement

- Our equivalent spatial resolution is high, and the 3D geometry is more complex than conventional RFID-based fingerprinting.
- The study can be applied to garment and shoe fitting setups with larger data sets of human study.
- Even higher spatial resolution of geometry recognition can be potentially achieved by adapting the system to mmID with higher carrier frequency.